

$SU(2)$

2 = fundamental rep.

Think spin $|\uparrow\rangle$ & spin $|\downarrow\rangle$

Any $SU(2)$ matrix can be written

as lin. comb of $\sigma^i = \left\{ \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right\}$

$$\tau^i \equiv \frac{\sigma^i}{2}$$

τ^i are generators of $SU(2)$.

Constructing invariants,

$$\bar{2} \otimes 2 = 1 \oplus 3$$

$s = \frac{1}{2}$ $\uparrow$ is $\hat{z}$ -projection of $\begin{vmatrix} \uparrow \\ \downarrow \end{vmatrix}$

$$|s = \frac{1}{2}\rangle \otimes |s = \frac{1}{2}\rangle = |s = 0\rangle \oplus |s = 1\rangle$$

$$\begin{array}{c} |\uparrow\uparrow\rangle \\ \frac{1}{\sqrt{2}}(|\uparrow\downarrow\rangle + |\downarrow\uparrow\rangle) \\ \underbrace{\quad\quad\quad}_{s=1} \\ |\downarrow\downarrow\rangle \end{array} \quad \frac{1}{\sqrt{2}}(|\uparrow\downarrow\rangle - |\downarrow\uparrow\rangle)$$

Same algebra as $SU(2)$ where $\overset{\text{spin}}{\text{angular momentum}}$ acts exactly like fundamental reps.

$$|2\rangle \times |\bar{2}\rangle = |1\rangle \oplus |3\rangle$$

"2" v_i = fundamental

" $\bar{2}$ " $\bar{v}_j$ = antifundamental

$$i, j = 1, 2$$

$$\text{singlet} \quad \bar{v}_j \delta_{ji} v_i = \bar{v}_i v_i \quad \begin{array}{c} 2 \times 2 \text{ or } N \times N \\ \downarrow \end{array}$$

$$SU(2): v_i \rightarrow U_{ai} v_i, \quad \bar{v}_j \rightarrow \bar{v}_j (U_{aj})^\dagger$$

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$$\boxed{\bar{v}_i v_i} \Rightarrow \bar{v}_i (U_{ai})^\dagger U_{ai} v_i$$

$$\boxed{= \bar{v}_i v_i}$$

Adjoint rep.

$$\bar{v}_j \epsilon^{ji} v_i \Rightarrow \bar{v}_b (U_{jb})^\dagger \epsilon^{ji} U_{ia} v_a$$

not invariant $\left[(U_{jb})^\dagger U_{ia} \right] \bar{v}_b \epsilon^{ji} v_a \rightarrow$ show that

$$\bar{v}_j \epsilon^{ji} v_i \rightarrow \epsilon^{abc} (\bar{v}_j \epsilon^{ji} v_i)$$

$$[\tau^i, \tau^j] = i \epsilon^{ijk} \tau^k$$

ϵ^{ijk} are structure constants of $SU(2)$
by def.

$$([t^a, t^b] = i f^{abc} t^c)$$

$$N^2 - 1 \rightarrow \bar{v}_b (U_{jb})^\dagger \epsilon^{ji} U_{ia} v_a$$

$$\text{If } j=i, \rightarrow 0$$

dimension is 1
singlet $\rightarrow \bar{v}_b (U_{jb})^\dagger \delta^{ji} U_{ia} v_a$

$N \times N$ tensor

Contract

$$\begin{array}{c} \bar{v}_b v_a \\ \uparrow \uparrow \\ N \quad N \end{array}$$

N^2 object

$$\bar{v}_b \epsilon^{ba} v_a \quad \begin{array}{c} -1 \text{ singlet} \\ N^2 - 1 \text{ object} \end{array}$$

$\hookrightarrow$ adjoint rep. by dimensions

ψ transforms in rep. r .

$$\mathcal{L} \supset \bar{\psi} i \not{D} \psi$$

$$D_\mu = \partial_\mu - i g' Q \gamma^\mu$$

$$- i g \frac{t^a}{r} \gamma^\mu$$

$$-ig t_r^a \gamma^\mu$$

t^i are rep. t_r^a for $r=2, \bar{2}$.

$(t^b)_{ac} = if^{abc}$ are rep. for adj.

adj. is an $N \times N$ matrix, traceless

Acting $N \times N$ matrix by $(t^b)_{ac}$ gives another $N \times N$ matrix

Gluons transform as adjoint.

Representation theory.

HW problem: Global symmetry?

Fields that carry extra index.

$$\hookrightarrow (e, \mu, \tau) = \boxed{e_i}, \quad i=1, \dots, 3$$

column vector valued field

IOW, field value is column vector

matrix-valued fields with 2 flavor indices

scalar ϕ_{ij}

Masses: $(M_{ijke}^2) \phi_{ij} \phi_{ke}$

When you make global symmetries gauged, still think in terms of **column vector valued** fermion + scalar fields **matrix valued** vector fields.

$A_\mu = \underbrace{A_\mu^a t^a}_{\text{matrix value for given } x}$ matrices have restrictions to ensure the field has a "minimal" level of being matrix valued.

This is motivation for studying group theory.

Start with set of elements + obtain some unknown mathematical structure.

Identity: e element.

...numerical structure.
Identity: e element.

But not yet interesting.

Another element: a .

Need introduce a composition operation
"how do two elements interact"

Every 2-element group is $\mathbb{Z}_2$

1 2	e	a
e	e	a
a	a	e

3 elements:

Keep closure.

Inversion. $\mathbb{Z}_3$ distinct from $\mathbb{Z}_2 + e$.

Most interesting aspect:

Introduce a notion of infinitesimal group element.

Two group elements can be infinitesimally close to each other.

Infinitesimal nature is carried by parameter α^a but group structure is evident already in the "basis" expansion.

$SU(N)$ = $N \times N$ matrices unitary.

$$SU(2) \ni \begin{pmatrix} 1 & 0.98 \\ -0.72 + 0.3i & 0.26 + 0.7i \end{pmatrix} = A$$

$$SU(2) \ni \begin{pmatrix} 1 & 0.980001 \\ -0.720001 + 0.300001i & 0.26 + 0.700001i \end{pmatrix} = B$$

Close if $A = \underbrace{\alpha^a}_{\text{scaling}} \underbrace{T^a}_{\text{basis matrices}} + \underbrace{B = (\alpha + \epsilon)^a T^a}_{\text{infinitesimal}}$

$\uparrow$ $\underbrace{\hspace{1cm}}$ $\uparrow$
 scaling basis infinitesimal
 matrices

Group structure is manifest in how t^a act with each other.

For example, $\alpha \rightarrow I$, then $\epsilon \neq 0$.

Each t^a is a unique "direction" in the $N \times N$ matrix space.

If all $t^a = \left\{ \begin{pmatrix} (2 \times 2) & 0 \\ 0 & (3 \times 3) \end{pmatrix} \right\}$

not minimal.

Conversely, subset of t^a is insufficient. = need closure.